

A-Level

Mathematics

MM05 Mechanics 5 Final Mark scheme

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Q	Solution	Mark	Total	Comment
1 (a)	2.45			
	$Period = 2\pi \sqrt{\frac{2.45}{9.8}}$	M1		M1: Uses formula with correct
	$=\pi$			length.
		A1		A1: Correct period.
	$= 3.14 \mathrm{s}$		2	
1 (b)	π		_	
	$2 \times 2 \times 2.45 \times \frac{10}{10}$	M1		M1: Correct distance found.
	Average Speed = $\frac{2 \times 2 \times 2.45 \times \frac{\pi}{10}}{\pi}$	A1		A1: Correct expression for
	$= 0.98 \text{ m s}^{-1}$	A1	3	average speed. A1: Correct average speed.
	0.2011.5	AI	3	Al. Contest average speed.
1 (c)	π (2)			
	$\theta = \frac{\pi}{10} \cos(2t)$	M1		M1: Correct expression for θ .
		A 4		
	$v = -\frac{2.45\pi}{5}\sin(2t)$	A1		A1: Correct expression for
	5	dM1		velocity. dM1: Forming equation to find <i>t</i> .
	$1.2 = \frac{2.45\pi}{5}\sin(2t)$			
	5	A 4		
	$t = \frac{1}{2} \sin^{-1} \left(\frac{5 \times 1.2}{2.45 \pi} \right) = 0.4469$	A1		A1: Correct time.
	- ()	A1		A1: Correct θ .
	$\theta = 0.197$		5	
	OR			
	$\frac{1}{2}m \times 1.2^2 = m \times 9.8 \times 2.45 \left(\cos\theta - \cos\left(\frac{\pi}{10}\right)\right)$	(M1)		M1: Energy equation with two terms correct.
	$2^{m \times 1.2} - m \times 9.0 \times 2.45 (\cos \theta - \cos(10))$	(A1)		A1: Correct terms but allow sign
	0.72 (π)	(A1)		errors.
	$\cos\theta = \frac{0.72}{24.01} + \cos\left(\frac{\pi}{10}\right)$	(dM1)		A1: Correct equation.
	$\theta = 0.195$	(1 1)	(5)	dM1: Solving for θ .
	0R	(A1)	(5)	A1: Correct value of θ .
		(M1)		M1: Use of $v^2 = \omega^2 (a^2 - x^2)$
	$1.2^{2} = 2^{2} \left(\left(\frac{2.45\pi}{10} \right)^{2} - \left(2.45\theta \right)^{2} \right)$	(A1)		with consistent terms.
		(A1)		A1: Correct terms but possible
	$1 \left(2.45\pi \right)^2 \left(1.2 \right)^2$	(dM1)		sign errors.
	$\theta = \frac{1}{2.45} \sqrt{\left(\frac{2.45\pi}{10}\right)^2 - \left(\frac{1.2}{2}\right)^2}$	(A1)		A1: Correct terms.
		(111)	(5)	dM1: Solving for θ .
	= 0.197 Total		10	A1: Correct value of θ .
	lotal		10	

Q	Solution	Mark	Total	Comment
2 (a)	$T_1 = 0.4g + T_2$			
	$\frac{49}{0.5}(d-0.5) = 0.4g + \frac{49}{0.5}(2-d-0.5)$	M1 A1		M1: Three force equation with at least two terms correct.
	98d - 49 = 3.92 + 147 - 98d $196d = 199.92$	dM1		A1: Correct equation. dM1: Solving for <i>d</i> . A1: Correct <i>d</i> .
	<i>d</i> = 1.02	A1	4	
2 (b)	$0.4\frac{d^2x}{dt^2} = T_2 + 0.4g - T_1$			
	$= \frac{49}{0.5} (2 - 1.02 - x - 0.5) + 0.4 \times 9.8 - \frac{49}{0.5} (x + 1.02 - 0.5)$ $= 47.04 - 98x + 3.92 - 98x - 50.96$	M1A1 A1		M1: Equation of motion with at least two terms correct. A1: Correct terms but possible sign errors. A1: Correct equation.
	$= -196x$ $\frac{d^2x}{dt^2} = -490x$	A1		A1: Correct simplified differential equation.
	$\text{Period} = \frac{2\pi}{\sqrt{490}} = \frac{\pi\sqrt{10}}{35}$	A1	5	A1: Correct period from correct working.
2 (c) (i)	$v_{\rm max} = \sqrt{490} \times 0.05 = \frac{7\sqrt{10}}{20} = 1.11 \mathrm{m s^{-1}}$	M1A1	2	M1: Use of $a\omega$. A1: Correct max speed.
2 (c) (ii)	$v^2 = 490(0.05^2 - 0.025^2) = \frac{147}{160}$	M1A1		M1: Use of $v^2 = \omega^2 (a^2 - x^2)$ with
	= 0.91875 v = $\sqrt{0.91875} = 0.959 \text{ m s}^{-1}$	A1	3	correct <i>a</i> . A1: Correct equation. A1: Correct speed.
	Total		14	

Q	Solution	Mark	Total	Comment
3 (a)	$EPE = \frac{4mg}{2 \times 1} \left(\sqrt{x^2 + y^2} - 1 \right)^2$	M1		M1: EPE in terms of x and y .
	$= 2mg\left(\sqrt{x^2 + 16 - 8x^2 + x^4} - 1\right)^2$	A1		A1: EPE in terms of x .
	$=2mg\left(\sqrt{16-7x^{2}+x^{4}}-1\right)^{2}$	A1		A1: EPE expanded correctly.
	$= 2mg\left(17 - 7x^{2} + x^{4} - 2\sqrt{16 - 7x^{2}} - 6x^{2}\right)$ $GPE = mgy = mg(4 - x^{2})$ $V = mg\left(38 - 15x^{2} + 2x^{4} - 4\sqrt{16 - 7x^{2} + x^{4}}\right)$	B1 A1	5	B1: Correct GPE. A1: Correct final result from correct working.
3 (b)	$\frac{dV}{dx} = mg\left(-30x + 8x^3 - \frac{8x^3 - 28x}{\sqrt{16 - 7x^2 + x^4}}\right)$	M1A1		M1: Differentiates with no more than one error. A1: Correct derivative.
	$x = 2, \frac{dV}{dx} = 0$	dM1		dM1: Substitutes $x = 2$.
	dx So there is a position of equilibrium when $x = 2$.	A1	4	A1: Obtains correct conclusion.
3 (c)	At $x = 1.9 \frac{dV}{dx} = -2.99mg$	M1		M1: Substitutes a value of x just less than 2.
	At $x = 2.1 \frac{dV}{dx} = 3.94mg$	M1		M1: Substitutes a value of x just greater than 2.
	As increasing this corresponds to a minimum value of V and hence is a position of stable equilibrium.	A1	3	A1: Uses values to reach the correct conclusion.
	OR $\frac{d^2 V}{dx^2} = mg \begin{pmatrix} 24x^2 - 30x \\ +\frac{(8x^3 - 28x^2)(2x^3 - 7)}{(\sqrt{16 - 7x^2 + x^4})^{1.5}} \\ +\frac{(28 - 24x^2)}{\sqrt{16 - 7x^2 + x^4}} \end{pmatrix}$	(M1) (A1)		M1: Second derivative of the correct format. A1: Correct second derivative.
	At $x = 2$, $\frac{d^2V}{dx^2} = 34mg$ This corresponds to a minimum value of V and hence is a position of stable equilibrium.	(A1)	(3)	A1: Correct value at $x = 2$ and correct conclusion.
	Total		12	

Q	Solution	Mark	Total	Comment
4 (a)	$1 = \sin 2t$	M1		M1: Using $r = 1$ to form an equation.
	$t = \frac{\pi}{4} + n\pi$	A1		A1: Finding <i>t</i> .
	$\dot{r} = 2\cos 2t$	B1		B1: Correct $\dot{\theta}$.
	$\dot{\theta} = 2$ $\ddot{\theta} = 0$			
	$\vec{\theta} = 0$ $\vec{r}\dot{\theta} + 2\dot{r}\dot{\theta} = 8\cos 2t$	• • •		
		M1		M1: Expression transverse component.
	$\cos\!\left(\frac{\pi}{2} + 2n\pi\right) = 0$	A1	5	A1: Obtaining zero from correct working.
	OR			
	$1 = \sin \theta$	(M1)		M1: Using $r = 1$ to form an equation.
	$\cos\theta = 0$	(A1)		A1: Finding $\cos\theta$.
	$\dot{r} = 2\cos\theta$			
	$\dot{\theta} = 2$	(B1)		B1: Correct $\dot{\theta}$.
	$\ddot{\theta} = 0$	(M1)		M1: Expression transverse component.
	$r\ddot{\theta} + 2\dot{r}\dot{\theta} = 8\cos\theta = 0$	(A1)	(5)	A1: Obtaining zero from correct working.
4 (b)	$\ddot{r} = -4\sin 2t$	M1		M1: Finding radial component.
	$\ddot{r} - r\dot{\theta}^2 = -4\sin 2t - 4\sin 2t$ $= -8\sin 2t$	A1		A1: Correct radial component.
	$0 = -8\sin 2t$	M1		M1: Forming equation to find <i>t</i> .
	$t = 0 + \frac{n\pi}{2}$	A1	4	A1: Correct time(s).
4 (c)	$r\dot{\theta} = 2\sin 2t$	M1		M1: Finding transverse component of the
	$\sin(n\pi) = 0$			velocity.
	$r\dot{\theta} = 0$	A1	2	A1: Correct conclusion from correct working.
	Total		11	

Q	Solution	Mark	Total	Comment
5	$m\frac{d^2x}{dt^2} = mg - \frac{2.5mx}{0.5} - 2m\frac{dx}{dt}$	M1A1		M1: Forming equation of motion, with at least two terms correct. A1: Correct differential equation.
	$\frac{d^2x}{dt^2} + 2\frac{dx}{dt} + 5x = g$ $PI x = \frac{g}{5}$	B1		B1: Correct PI.
	$CF \lambda^2 + 2\lambda + 5 = 0$	M1		M1: Solving auxiliary equation.
	$\lambda = \frac{-2 \pm \sqrt{2^2 - 4 \times 1 \times 5}}{2 \times 1} = -1 \pm 2i$	A1		A1: Correct roots.
	$x = e^{-t} \left(A\sin 2t + B\cos 2t\right) + \frac{g}{5}$	A1		A1: Correct general solution.
	$t = 0, x = 0$ $0 = B + \frac{g}{5}$	M1		M1: Finding one constant.
	B = -g/5	A1		A1: Correct constant.
	$\dot{x} = -e^{-t} (A\sin 2t + B\cos 2t) + e^{-t} (2A\cos 2t - 2B\sin 2t) \dot{x} = e^{-t} ((-A - 2B)\sin 2t)$	M1		M1: Finding derivative.
	$+(-B+2A)\cos 2t)$	A1		A1: Correct derivative.
	$t = 0, \dot{x} = 0$ $0 = -B + 2A$ $A = -\frac{g}{10}$	A1		A1: Second constant correct.
	$x = ge^{-t} \left(-\frac{\sin 2t}{10} - \frac{\cos 2t}{5} \right) + \frac{g}{5}$ $\dot{x} = ge^{-t} \left(\frac{5\sin 2t}{8} \right)$	M1		M1: Finding time for zero speed.
	$\dot{x} = 0 \Longrightarrow t = \frac{\pi}{2}$	A1		A1: Correct time.
	$x = ge^{-\frac{\pi}{2}} \left(-\frac{\sin \pi}{10} - \frac{\cos \pi}{5} \right) + \frac{g}{5}$ May Length of String	M1		M1: Using time to find max length.
	Max Length of String = $\frac{g}{5} \left(1 + e^{-\frac{\pi}{2}} \right) + 0.5 = 2.87 \text{ m}$	A1		A1: Correct maximum length.
			15	
	Total		15	

Q	Solution	Mark	Total	Comment
6 (a)	$mg\delta t = (m + \delta m)(v + \delta v) + (-\delta m)(v + \delta v + U) - mv$	M1 A1		M1: Use of momentum-impulse equation. (Must have $v+U$) A1: Correct equation.
	$mg \delta t = m \delta v - U \delta m$ $mg = m \frac{dv}{dt} - U \frac{dm}{dt}$ $\frac{dm}{dt} = -\lambda, m = M - \lambda t$	dM1 M1		dM1: Forming differential equation. M1: Expression for <i>M</i> in terms of <i>t</i> .
	$mg = m\frac{dv}{dt} + \lambda U$ $\frac{dv}{dt} = g - \frac{\lambda U}{M - \lambda t}$	A1	5	A1: Correct result from correct working.
6 (b)	$t = 0, m = M, \frac{dv}{dt} < 0$ $g - \frac{\lambda U}{M} < 0$	M1 dM1		M1: Statement that acceleration is less than zero. dM1: Use of time as zero.
	$U > \frac{Mg}{\lambda}$	A1	3	A1: Correct result from correct working.
6 (c)	$\int 1 dv = \int g - \frac{\lambda U}{M - \lambda t} dt$			
	$v = gt + U\ln(M - \lambda t) + c$	M1A1		M1: Integrating to obtain linear and ln
	$t = 0, v = \frac{U}{20} \Longrightarrow c = \frac{U}{20} - U \ln M$ $v = gt + U \ln\left(\frac{M - \lambda t}{M}\right) + \frac{U}{20}$	A1		terms. A1: Correct integral. A1: Correct constant.
	$t = \frac{M}{10\lambda}$	M1		M1: Correct time.
	$v = \frac{gM}{10\lambda} + \frac{3gM}{2\lambda} \ln\left(\frac{9}{10}\right) + \frac{3gM}{40\lambda}$ $= \frac{3gM}{2\lambda} \ln\left(\frac{9}{10}\right) + \frac{7gM}{40\lambda}$	A1	5	A1: Correct velocity.
			42	
	Total		13	